## Contractive Systems Inspired GNNs

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#### Graphs are everywhere



#### Molecule structure



Reference graph some notes I wrote



Connectivity of neurons in the brain

Citation graph of some papers I saved







Usual structure of GNNs  $F^{(0)} = F$  $F^{(l+1)} = T_l\left(F^{(l)}, A\right), l = 0, \dots L - 1$  $R = MLP(F^{(L)}) =: GNN(F, A)$ 

Invariant  $GNN(F, A) = GNN(PF, PAP^T)$  $PGNN(F, A) = GNN(PF, PAP^T)$  Equivariant

#### Usual structure of GNNs



Are (learnable) functions



Source : <u>https://geometricdeeplearning.com/lectures/</u>

#### Adversarial attacks



on Facebook

### Adversarial attacks $F_* = F + \delta F, \quad \|\delta F\|_F \le \varepsilon_1$ $A_* = A + \delta A, \quad \|\delta A\|_0 \le \varepsilon_2$

Attacks do not break the properties of symmetry generally

Goal:  $GNN(F, A) \approx GNN(F_*, A_*)$ 

#### Remark on Nuclear Norm

 $A \in \overline{\{0,1\}^{n \times n}} \implies ||A||_0 = \#\{i, j \in \{1, ..., n\}: A_{ij} \neq 0\} = ||\operatorname{vec}(\overline{A})||_{\ell^1}$ 



The 1-norm of the vectorisation is better suited for what we do, and we will use such norm instead of the nuclear norm.

## Our proposed architecture: CSGNN



$$\begin{split} \left(F^{(0)}, A^{(0)}\right) &:= \left(\mathcal{K}\left(F_{*}\right), A_{*}\right) \\ \Psi^{h_{i}}_{X_{i}}(F, A) &= F - h_{i}G(A)^{T}\sigma\left(G(A)FW_{i}\right)W_{i}^{T} \\ \Psi^{h_{i}}_{Y_{i}}(A) &= A + h_{i}\sigma\left(M_{i}(A)\right) \end{split}$$

#### Linear equivariant vector field

$$\begin{split} M(A) &= k_1 A + k_2 \operatorname{diag}(\operatorname{diag}(A)) + \frac{k_3}{2n} (A \mathbf{1}_n \mathbf{1}_n^\top + \mathbf{1}_n \mathbf{1}_n^\top A) + k_4 \operatorname{diag}(A \mathbf{1}_n) \\ &+ \frac{k_5}{n^2} (\mathbf{1}_n^\top A \mathbf{1}_n) \mathbf{1}_n \mathbf{1}_n^\top + \frac{k_6}{n} (\mathbf{1}_n^\top A \mathbf{1}_n) I_n + \frac{k_7}{n^2} (\mathbf{1}_n^\top \operatorname{diag}(A)) \mathbf{1}_n \mathbf{1}_n^\top \\ &+ \frac{k_8}{n} (\mathbf{1}_n^\top \operatorname{diag}(A)) I_n + \frac{k_9}{2n} (\operatorname{diag}(A) \mathbf{1}_n^\top + \mathbf{1}_n (\operatorname{diag}(A))^\top) \end{split}$$

 $M(PAP^T) = PM(A)P^T, \quad (M(A))^T = M(A)$ 

#### Contractivity of feature updates

If  $\sigma : \mathbb{R} \to \mathbb{R}$  is a non-decreasing 1-Lipschitz function, then the explicit Euler update is contractive in the F-norm when  $h_i \leq 2/||W_i||_2^2$ :  $\left\|\Psi_{X_i}^{h_i}(\mathbf{F} + \delta \mathbf{F}, \mathbf{A}) - \Psi_{X_i}^{h_i}(\mathbf{F}, \mathbf{A})\right\|_F \leq \|\delta \mathbf{F}\|_F,$  $\delta \mathbf{F} \in \mathbb{R}^{n \times c}$ 

#### Contractivity of adjacency updates

If  $\sigma : \mathbb{R} \to \mathbb{R}$  is a non-decreasing 1-Lipschitz function, then the explicit Euler update is contractive in the vectorized 1-norm when

$$h_i \leq \frac{2}{\left(2\sum_{i=2}^9 |k_i|\right) - \alpha}, \quad k_1 = \left(\alpha - \sum_{i=2}^9 |k_i|\right), \ \alpha \leq 0.$$

This means that:

$$\left\| \operatorname{vec}(\Psi_{Y_i}^{h_i}(\boldsymbol{A} + \delta \boldsymbol{A})) - \operatorname{vec}(\Psi_{Y_i}^{h_i}(\boldsymbol{A})) \right\|_1 \le \left\| \operatorname{vec}(\delta \boldsymbol{A}) \right\|_1, \\ \delta \boldsymbol{A} \in \mathbb{R}^{n \times n}$$

#### Robustness of the network

If the assumptions of the two previous theorems hold, and  $A_{*}^{(0)} = A^{(0)} + \delta A, \ F_{*}^{(0)} = F^{(0)} + \delta F$  $\|\delta \boldsymbol{F}\|_F \leq \varepsilon_1, \|\operatorname{vec}(\delta \boldsymbol{A})\|_1 \leq \varepsilon_2,$ it follows  $d\left(\mathcal{D}\left(\mathbf{F}^{(0)}, \mathbf{A}^{(0)}\right), \mathcal{D}\left(\mathbf{F}^{(0)}_{*}, \mathbf{A}^{(0)}_{*}\right)\right) := \left\|\operatorname{vec}\left(\mathbf{A}^{(L)}\right) - \operatorname{vec}\left(\mathbf{A}^{(L)}_{*}\right)\right\|_{1} + \left\|\mathbf{F}^{(L)} - \mathbf{F}^{(L)}_{*}\right\|_{F}$  $\leq \varepsilon_1 + \varepsilon_2 \left( 1 + \sum_{i=1}^{L} \operatorname{Lip}\left(X_{i,\mathbf{F}^{(i-1)}}\right) h_i \right)$  $=: \varepsilon_1 + c (h_1, \ldots, h_L) \varepsilon_2.$ 

#### Experimental setup

Hyperparameter	Range	Distribution	
input/output embedding learning rate	$[10^{-5}, 10^{-2}]$	uniform	
node dynamics learning rate	$[10^{-5}, 10^{-2}]$	uniform	
adjacency dynamics learning rate	$[10^{-5}, 10^{-2}]$	uniform	
input/output embedding weight decay	$[5\cdot 10^{-8}, 5\cdot 10^{-2}]$	log uniform	
node dynamics weight decay	$[5 \cdot 10^{-8}, 5 \cdot 10^{-2}]$	log uniform	
adjacency dynamics weight decay	$[5 \cdot 10^{-8}, 5 \cdot 10^{-2}]$	log uniform	
input/output embedding dropout	[0, 0.6]	uniform	
node dynamics dropout	[0, 0.6]	uniform	
share weights between time steps	$\{yes, no\}$	discrete uniform	
step size $h$	$[10^{-2}, 1]$	log uniform	
adjacency contractivity parameter $\alpha$	[-2,0]	uniform	
#layers $L$	$\{2, 3, 4, 5\}$	discrete uniform	
#channels $c$	$\{8, 16, 32, 64, 128\}$	discrete uniform	

#### Some experimental results

Method	Cora nettack metattack random		Citeseer nettack metattack random			
CSGNN <sub>noAdj</sub>	81.90	70.25	77.19	82.20	70.17	71.28
CSGNN	83.29	74.46	78.38	84.60	72.94	72.70



We target the nodes with degree at least 10 and flip few of their incident edges

Node classification accuracy (%) of ECSGNN and other baselines, under a targeted attack generated by nettack. The horizontal axis describes the number of perturbations per node.

#### Some experimental results



Classification accuracy for The Pubmed dataset using Nettack as attack method.



The adjacency matrix is attacked by adding random fake edges, from 0% to 100% of the number of edges in the true one.

# Thank you for the attention

Eliasof, M., M., D., Sherry, F., & Schönlieb, C. B. (2023). Contractive Systems Improve Graph Neural Networks Against Adversarial Attacks. *arXiv preprint*.

Scan for the preprint

